

The massive scalar field in a closed Friedmann universe model – new rigorous results

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Abstract

For the minimally coupled scalar field in Einstein’s theory of gravitation we look for the space of solutions within the class of closed Friedmann universe models. We prove $D \geq 1$, where D is the dimension of the set of solutions which can be integrated up to $t \rightarrow \infty$ ($D > 0$ was conjectured by PAGE (1984)). We discuss concepts like “the probability of the appearance of a sufficiently long inflationary phase” and argue that it is primarily a probability measure μ in the space V of solutions (and not in the space of initial conditions) which has to be applied. μ is naturally defined for Bianchi-type I cosmological models because V is a compact cube. The problems with the closed Friedmann model (which led to controversial claims in the literature) will be shown to originate from the fact that V has a complicated non-compact non-Hausdorff Geroch topology: no natural definition of μ can be given.

We conclude: the present state of our universe can be explained by models of the type discussed, but thereby the anthropic principle cannot be fully circumvented.

Für das minimal gekoppelte Skalarfeld in Einsteinscher Gravitations-theorie betrachten wir den Lösungsraum in der Klasse der geschlossenen Friedmannmodelle des Universums. Wir beweisen, daß $D \geq 1$ gilt, wobei D die Dimension der Menge derjenigen Lösungen ist, die sich bis $t \rightarrow \infty$ integrieren lassen. ($D > 0$ war von PAGE (1984) vermutet worden.) Wir diskutieren Begriffe wie “die Wahrscheinlichkeit des Auftretens einer hinreichend langen inflationären Phase” und argumentieren, daß man primär ein Wahrscheinlichkeitsmaß μ im Raum der Lösungen V (und nicht im Raum der Anfangswerte) anwenden muß. Für kosmologische Modelle vom Bianchi-Typ I gibt es eine natürliche Definition für μ , da dort V ein kompakter Würfel ist. Die Probleme mit dem geschlossenen Friedmannmodell (die zu Kontroversen in der Literatur führten) ergeben sich aus der Tatsache, daß V dort eine komplizierte Geroch-Topologie hat, die weder kompakt noch hausdorffsch ist, so daß sich keine natürliche Definition für μ angeben läßt.

Wir schließen: Zwar läßt sich der heutige Zustand unseres Universums durch Modelle des hier diskutierten Typs erklären, jedoch läßt sich dabei das anthropische Prinzip nicht völlig umgehen.

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1 Introduction

We consider a closed Friedmann cosmological model,

$$ds^2 = g_{ij}dx^i dx^j = dt^2 - a^2(t)[dr^2 + \sin^2 r(d\psi^2 + \sin^2 \psi d\chi^2)], \quad (1)$$

with the cosmic scale factor $a(t)$. We apply Einstein’s General Relativity Theory and take a minimally coupled scalar field ϕ without self-interaction

as source, i.e., the Lagrangian is ($\hbar = c = 1$)

$$\mathcal{L} = \frac{R}{16\pi G} + \frac{1}{2}g^{ij}\nabla_i\nabla_j - \frac{1}{2}m^2\phi^2. \quad (2)$$

R is the scalar curvature, G Newton's constant, and m the mass of the scalar field. $\delta\mathcal{L}/\delta\phi = 0$ yields

$$(m^2 + \square)\phi = 0, \quad \square \equiv g^{ij}\nabla_i\nabla_j \quad (3)$$

where \square is the covariant D'Alembertian.

$$\delta\mathcal{L}\sqrt{-\det g_{kl}}/\delta g^{ij} = 0$$

yields Einstein's equation

$$R_{ij} - \frac{R}{2}g_{ij} = 8\pi GT_{ij}, \quad T_{ij} \equiv \nabla_i\phi\nabla_j\phi - \frac{1}{2}\left(\nabla^k\phi\nabla_k\phi - m^2\phi^2\right), \quad (4)$$

with Ricci tensor R_{ij} . It is the aim of the present paper to give some new rigorous results about the space V of solutions of eqs. (3.4) with metric (1) (Scts. 2, 3, 4) and to discuss them in the context of cosmology (Sct. 5): the probability of the appearance of a sufficiently long inflationary phase and the anthropic principle.

SCHRÖDINGER (1938) (here cited from SCHRÖDINGER (1956)) already deals with the massive scalar field in the closed Friedmann universe, but there the back-reaction of the scalar field on the evolution of the cosmic scale factor had been neglected. 35 years later the model enjoyed a renewed interest, especially as a semi-classical description of quantum effects, cf. e.g. FULLING (1973), FULLING and PARKER (1974), STAROBINSKY (1978), BARROW and MATZNER (1980), GOTTLÖBER (1984a, b) and HAWKING and LUTTRELL (1984). One intriguing property - the possibility of a bounce, i.e., a positive local minimum of the cosmic scale factor - made it interesting in connection with a possible avoidance of a big bang singularity $a(t) \rightarrow 0$. The existence of periodic solutions $(\phi(t), a(t))$ of eqs. (1, 3, 4)

became clear in 1984 by independent work of HAWKING (1984a, b) and GOTTLÖBER and SCHMIDT (1984). In PAGE (1984) it was conjectured (I see no chance to exclude that most of the sets

$$S_{n_1 \dots n_j}$$

eq. (29) of that paper are empty) that besides the periodic solutions also a fractal set of Hausdorff dimension $D > 0$ of aperiodic perpetually bouncing universes exist. We shall prove this conjecture in a stronger version ($D \geq 1$) in Sct. 3.

The existence of an inflationary phase (defined by $|dh/dt| \ll h^2$, where $h = d(\ln a)/dt$ is the Hubble parameter) in the cosmic evolution is discussed in many papers to that model, cf e.g. BELINSKY et al. (1985), BELINSKY and KHALATNIKOV (1987), PAGE (1987), GOTTLÖBER and MÜLLER (1987), and GOTTLÖBER (1988).

Soon it became clear that the satisfactory results obtained for the spatially flat model – the existence of a naturally defined measure in the space of solutions and with this measure the very large probability to have sufficient inflation – cannot be generalized to the closed model easily. We shall turn to that point in Sct. 5.

2 Some closed-form approximations

We consider the system (3, 4) with metric (1). Sometimes, one takes it as an additional assumption that ϕ depends on the coordinate t only, but it holds (cf. TURNER 1983): the spatial homogeneity of metric (1) already implies this property.

Proof: For $i \neq j$ we have $R_{ij} = g_{ij} = 0$ and, therefore, $\nabla_i \phi \nabla_j \phi = 0$: locally, ϕ depends on one coordinate x^i only. Supposed $i \neq 0$, then $g^{ij} T_{ij} - 2T_{00} =$

$m^2\phi^2$. The l.h.s. depends on t only. For $m \neq 0$ this is already a contradiction. For $m = 0$ we have $R_{ij} = \nabla_i\phi\nabla_j\phi$, which is a contradiction to the spatial isotropy of R_{ij} , q.e.d.

We always require $a(t) > 0$, for otherwise the metric (1) is degenerated (“big bang”). Eqs. (3, 4) reduce to

$$m^2\phi + d^2\phi/dt^2 + 3hd\phi/dt = 0 \quad (5)$$

and

$$3(h^2 + a^{-2}) = 4\pi G[m^2\phi^2 + (d\phi/dt)^2]. \quad (6)$$

Eq. (6) is the 00 component of eq. (4), the other components are a consequence of it.

For the massless case $m = 0$ (i.e. stiff matter, pressure equals energy density), eqs. (5, 6) can be integrated. Let $\psi = d\phi/dt$, then eq. (5) implies $\psi a^3 = \text{const}$. Inserting this into eq. (6), we get

$$da/dt = \pm\sqrt{L^4/a^4 - 1}$$

with a constant $L > 0$ and $0 < a \leq L$. We get $a(t)$ via the inverted function up to a t translation

$$\pm t = \frac{1}{2}L \arcsin(a/L) - \frac{a}{2}\sqrt{1 - a^2/L^2}.$$

This is conformally equivalent to $L = R^2$, cf. STAROBINKY and SCHMIDT (1987) and BARROW and SIROUSSE-ZIA (1989). For $a \ll L$ we have $a \sim t^{1/3}$ and $\phi = \phi_0 + \phi_1 \ln t$. For $a = L$ we have a maximum of the function $a(t)$. $a(t) > 0$ is fulfilled for a t interval of length $\Delta t = \pi L/2$ only, and there is no bounce.

In which range can one except the massless case to be a good approximation for the massive case? To this end we perform the following substitutions:

$$\tilde{t} = t/\epsilon, \quad \tilde{a} = a/\epsilon, \quad \tilde{m} = m\epsilon, \quad \tilde{\phi} = \phi.$$

They do not change the differential equations. Therefore, to get a solution $a(t)$ with a maximum $a_{\max} = \epsilon \ll 1$ for m fixed, we can transform to a solution with $\tilde{a}_{\max} = 1$, $\tilde{m} = \epsilon m \ll m$ and apply solutions $\tilde{a}(\tilde{t})$ with $\tilde{m} = 0$ as a good approximation. Then $a(t) > 0$ is fulfilled for a t interval of length $\Delta t \approx \pi a_{\max}/2$ only. This is in quite good agreement with the estimate in eq. (22) of PAGE (1984). But in the contrary to the massless case it holds: to each $\epsilon > 0$ there exist bouncing solutions which possess a local maximum $a_{\max} = \epsilon$.

Let henceforth be $m > 0$. Then we use $\sqrt{4\pi G/3}\phi$ instead of ϕ as scalar field and take units such $m = 1$. With a dot denoting d/dt we finally get from eqs. (5, 6)

$$\phi + \ddot{\phi} + 3h\dot{\phi} = 0, \quad h^2 + a^{-2} = \phi^2 + \dot{\phi}^2. \quad (7)$$

$\phi \rightarrow -\phi$ is a Z_2 -gauge transformation (Z_2 is the two-point group). Derivating eq. (7) we can express ϕ and $\dot{\phi}$ as follows

$$\phi = \pm\sqrt{2 + 2\dot{a}^2 + a\ddot{a}}/\sqrt{3a^2}, \quad \dot{\phi} = \pm\sqrt{1 + \dot{a}^2 - a\ddot{a}}/\sqrt{3a^2}. \quad (8)$$

Inserting (8) into eq. (7) we get

$$a^2 \frac{d^3 a}{dt^3} = 4\dot{a}(1 + \dot{a}^2) - 3a\dot{a}\ddot{a} \pm 2a\sqrt{2 + 2\dot{a}^2 + a\ddot{a}}\sqrt{1 + \dot{a}^2 - a\ddot{a}}. \quad (9)$$

On the r.h.s. we have “+” if $\phi\dot{\phi} > 0$ and “−” otherwise. At all points t , where one of the roots becomes zero, “+” and “−” have to be interchanged.

To get the temporal behaviour for very large values $a \gg 1$ but small values $|h|$, we make the ansatz

$$a(t) = 1/\epsilon + \epsilon A(t), \quad \epsilon > 0, \quad \epsilon \approx 0. \quad (10)$$

In lowest order of ϵ we get from (9)

$$\frac{d^3 A}{dt^3} = \pm 2\sqrt{2 + \ddot{A}}\sqrt{1 - \ddot{A}}. \quad (11)$$

An additive constant to $A(t)$ can be absorbed by a redefinition of ϵ , eq. (10), so we require $A(0) = 0$. After a suitable translation of t , each solution of eq. (11) can be represented as

$$A(t) = \alpha t - t^2/4 + \frac{3}{8} \sin(2t), \quad |\alpha| \leq \pi/4. \quad (12)$$

$\alpha = \pi/4$ and $\alpha = -\pi/4$ represent the same solution, so we have a S^1 space of solutions (S^n is the n -dimensional sphere). $a(t) > 0$ is fulfilled for $A(t) > -1/\epsilon^2$, i.e. $|t| < 2/\epsilon$ only. In dependence of the value α , $A(t)$ has one or two maxima and, accordingly, null or one minimum. The corresponding intervals for α meet at two points, $\alpha \approx 0$ and $|\alpha| \approx \pi/4$, where one maximum and one horizontal turning point

$$\dot{a} = \ddot{a} = 0, \quad \frac{d^3a}{dt^3} \neq 0$$

exist.

3 The qualitative behaviour

Eq. (7) is a regular system: at $t = 0$ we prescribe a_0 , $\text{sgn } \dot{a}_0$, ϕ_0 , $\dot{\phi}_0$ fulfilling

$$a_0^2 (\phi_0^2 + \dot{\phi}_0^2) \leq 1$$

and then all higher derivatives can be obtained by differentiating:

$$|\dot{a}| = \sqrt{a^2(\phi^2 + \dot{\phi}^2) - 1}, \quad \ddot{\phi} = -3\dot{a}\dot{\phi}/a - \phi,$$

the r.h.s. being smooth functions. It follows

$$d/dt (h^2 + a^{-2}) = -6h(d\phi/dt)^2. \quad (13)$$

3.1 Existence of a maximum

The existence of a local maximum for each solution $a(t)$ already follows from the “closed universe recollapse conjecture”, but we shall prove it for our

model as follows: if we start integrating with $h \geq 0$ (otherwise, $t \rightarrow -t$ serves to reach that), then $h^2 + a^{-2}$ is a monotoneously decreasing function as long as $h \geq 0$ holds ($h\dot{\phi} = 0$ holds at isolated points t only), cf. eq. (13). We want to show that after a finite time, h changes its sign giving rise to a local maximum of $a(t)$. If this is not the case after a short time, then we have after a long time $h \ll 1$, $a \gg 1$, and eqs. (10, 12) become a good approximation to the exact solution. The approximate solution (10, 12) has already shown to possess a local quadratic maximum and this property is a stable one within C^2 perturbations. So the exact solution has a maximum, too, q.e.d.

3.2 The space of solutions

We denote the space of solutions for (1,7) by V and endow it with Geroch's topology (GEROCH 1969); see Sct. 4.3. for further details. Applying the result of Sct. 3.1., V can be constructed as follows: the set of solutions will not be diminished if we start integrating with $\dot{a}_0 = 0$. We prescribe

$$f = a_0^{-1} \quad \text{and} \quad g = (1 - a_0 \ddot{a}_0) \cdot \text{sgn}(\phi_0 \dot{\phi}_0), \quad (14)$$

then all other values are fixed. f and g are restricted by $f > 0$; $|g| \leq 3$, where $g = 3$ and $g = -3$ describe the same solution. Therefore

$$V = (\mathcal{R} \times S^1)/Q, \quad (15)$$

where \mathcal{R} denotes the real line (as topological space) and Q is an equivalence relation defined as follows:

Some solutions $a(t)$ have more than one (but at most countably many) extremal points, but each extremum defines one point in $\mathcal{R} \times S^1$; these are just the points being Q -equivalent.

Considering eqs. (7, 14) in more details, we get the following: for $|g| < 1$ we have a minimum and for $|g| > 1$ a maximum for $a(t)$.

$$\frac{d^3 a_0}{dt^3} > 0$$

holds for $0 < g < 3$. $a(t)$ is an even function for $g = 0$ and $g = \pm 3$ only. For $g = 0$ it is a symmetric minimum of $a(t)$ and ϕ is even, too. For $g = \pm 3$ it is a symmetric maximum of $a(t)$ and ϕ is odd. For $|g| = 1$ one has a horizontal turning point for $a(t)$. Time reversal $t \rightarrow -t$ leads to $g \rightarrow -g$.

3.3 From one extremum to the next

To prove our result, $D \geq 1$, where D is the dimension of the set of solutions which can be integrated up to $t \rightarrow \infty$, we need a better knowledge of the equivalence relation Q . To this end we define a map

$$p : \mathcal{R} \times S^1 \rightarrow \mathcal{R} \times S^1$$

as follows:

For $x = (f, g)$ we start integrating at $t = 0$. Let

$$t_1 = \min\{t | t > 0, \dot{a}(t) = 0\}.$$

For $t_1 < \infty$ we define

$$p(x) = \bar{x} = (\bar{f}, \bar{g}) = (f(t_1), g(t_1))$$

and otherwise p is not defined. (This notation applies only to this Sect. 3.)

In words: p maps the initial conditions from one extremal point of $a(t)$ to the next one. It holds: p is injective and xQy if and only if there exists an integer m such that $p^m(x) = y$.

Let $V_m \subset \mathcal{R} \times S^1$ be that subspace for which p^m is defined.

$$\{(f, g) | -1 < g \leq 1\} \subset V_1$$

means: a minimum is always followed by a maximum; $|g| < 1$ implies $|\bar{g}| \geq 1$. $V_2 \neq \emptyset$ follows from the end of Sct. 2. For $x = (f, g)$ we define $-x = (f, -g)$. With this notation it holds (see the end of Sct. 3.2)

$$p^m(V_m) = V_{-m} = -V_m,$$

and for $x \in V$ we have

$$p^m(-p^m(x)) = -x \quad \text{and} \quad p^{-m}(V_m \cap V_{-m}) = V_{2m}. \quad (16)$$

A horizontal turning point can be continuously deformed to a pair of extrema; such points give rise to discontinuities of the function p , but for a suitably defined nonconstant integer power m the function p^m is a continuous one. If $x \in V_1 \setminus \text{int}(V_1)$ (int denotes the topological interior), then $a(t)$ possesses a horizontal turning point. To elucidate the contents of these sentences we give an example:

For very small values f and \bar{f} we may apply eqs. (10, 12) to calculate the function p^m . In the approximation used, no more than 3 extremal points appear, so we have to consider

$$p^m, \quad m \in \{-2, -1, 0, 1, 2\}$$

only. f and \bar{f} approximately coincide, so we concentrate on the function $\bar{g}(g)$, see Fig. 1. The necessary power m is sketched at the curve. To come from m to $-m$, the curve has to be reflected at the line $\bar{g} = g$. Time reversal can be achieved, if it is reflected at $\bar{g} = -g$. V_1 is the interval $-1 < g \leq 2.8853$. The jump discontinuity of p at $g = 1$ and the boundary value $g = 2.8853$... are both connected with horizontal turning points $g, \bar{g} = \pm 1$. The shape of the function $\bar{g}(g)$ in Fig. 1 for $m = 1$ can be obtained by calculating the extrema of $A(t)$ (eq. (12)) in dependence of α and then applying eq. (14). For $m \neq 1$ one applies eq. (16).

Fig. 1. Poincare-return map for the closed Friedmann model, explanation see Sct. 3.3, and $m = n$.

3.4 The periodic solutions

The periodic solutions $a(t)$ are characterized by the fixed points of some p^m , $m \geq 2$. (p itself has no fixed points). The existence of them can be proved as follows: we start integrating at $t = 0$ with a symmetric minimum ($g = 0$) of $a(t)$ and count the number m of zeros of $\dot{\phi}(t)$ in the time interval $0 < t < t_2$, where $a(t_2)$ is the first local maximum of $a(t)$. m depends on $f = 1/a(0)$ and has jump discontinuities only at points where $\dot{\phi}(t_2) = 0$. For initial values $f = f_k$, where m jumps from k to $k + 1$, $a(t)$ is symmetric about $t = t_2$. But a function, which is symmetric about two different points, is a periodic one. We call them periodic solutions of the first type, they are fixed points of p^2 .

PAGE (1984) gives the numerically obtained result: $f_1 = 1/a_0$ with $a_0 = 0.76207\dots$ That f_k exists also for very large values k can be seen as follows: take solution (10, 12) with a very small value ϵ and insert it into eq. (8); we roughly get $m = 1/\epsilon\pi$.

Periodic solutions of the second type, fixed points of p^4 , which are not fixed points of p^2 , can be constructed as follows: we start with $g = 0$ but $f \neq f_k$ and count the number n of zeros of $\dot{\phi}(t)$ in the interval $0 < t < t_3$, where $a(t_3) > 0$ is next local minimum of $a(t)$. (For $f \approx f_k$, t_3 is defined by continuity reasons).

For $f = f^l$, n jumps from l to $l + 1$ and we have a periodic solution. Numerical evaluations yield $f^1 = 1/a_0$, $a_0 = 0.74720\dots$ The existence of f^l for very large values l is again ensured by solution (10, 12).

3.5 The aperiodic perpetually oscillating solutions

Now we look at the solutions in the neighbourhood of the periodic ones. Let $x_0 = (f_k, 0) \in V_2$ be one of the fixed points of p^2 ; $a_0(t)$, the corresponding periodic solution of the first type has no horizontal turning points. Therefore, p is smooth at x_0 . Let us denote the circle with boundary of radius ϵ around x_0 by $K(\epsilon)$. By continuity reasons there exists an $\epsilon > 0$ such that $K(\epsilon) \subset \text{int}(V_2 \cap V_{-2})$ and the first two extrema of the functions $a(t)$ corresponding to points of $K(\epsilon)$ are either maxima or minima. Let $R_0 = K(\epsilon)$ and for $n \geq 1$

$$R_n := R_0 \cap p^2(R_{n-1}) ; \quad R_{-n} := R_0 \cap p^{-2}(R_{1-n}) .$$

By assumption, $p^{\pm 2}$ is defined in R_0 , so R_m is a well-defined compact set with $x_0 \in \text{int } R_m$ for each integer m . It holds

$$R_{n+1} \subset R_n , \quad R_{-n} = -R_n$$

and

$$R_n = \{x | p^{2m}(x) \in R_0 \text{ for } m = 0, \dots, n\} , \\ R_\infty := \bigcap_{n=0}^{\infty} R_n$$

is a compact set with $x_0 \in R_\infty$.

For each $x \in R_\infty$, the corresponding solution $a(t)$ can be integrated up to $t \rightarrow \infty$. The last statement follows from the fact that the time from one extremum to the next is bounded from below by a positive number within the compact set R_0 , i.e., an infinite number of extrema can be covered only by an infinite amount of time. Analogous statements hold for $R_{-\infty} = -R_\infty$ and $t \rightarrow -\infty$.

Let us fix an integer $m \geq 1$. We start integrating at $x_\delta := (f_k, \delta) \in R_0$, $0 < \delta \leq \epsilon$.

$$\delta(m) := \max\{\delta | \delta \leq \epsilon, p^{2k}(x_\delta) \in R_0 \text{ for } k = 0, \dots, m\}$$

exists because of compactness, i.e., $x_{\delta(m)} \in R_m$ and there is an integer $k(m) \leq m$ such that

$$y(m) := p^{2k(m)} (x_{\delta(m)}) \in \delta R_0 ,$$

δR_0 being the boundary of R_0 .

$$j(m) := 1 , \quad \text{if } k(m) < m/2 , \quad \text{otherwise} = 0 .$$

The sequence

$$(y(m), j(m)) \subset S^1 \times Z_2$$

possesses a converging subsequence with

$$y(\infty) := \lim_{i \rightarrow \infty} y(m_i) , \quad j(\infty) := \lim_{i \rightarrow \infty} j(m_i) .$$

Now let us start integrating from $y(\infty)$ forward in time for $j(\infty) = 1$ and backwards in time for $j(\infty) = 0$. We consider only the case $j(\infty) = 1$, the other case will be solved by $t \rightarrow -t$. For each i with $m_i > 2m$ we have $y(m_i) \in R_m$, therefore, $y(\infty) \in R_m$ for all m , i.e., $y(\infty) \in R_\infty$. $y(\infty) \in \delta R_0$ and for all $n \geq 1$, $p^{2n}(y(\infty)) \in R_0$.

By continuously diminishing ϵ we get a one-parameter set of solutions $a_\epsilon(t)$, which can be integrated up to $t \rightarrow \infty$. (To this end remember that one solution $a(t)$ is represented by at most countably many points of R_0). Supposed $a_\epsilon(t)$ is a periodic function. By construction this solution has a symmetric minimum and there exist only countably many such solutions. Let $M = \{a(t) | a(0)\}$ is a minimum parametrized by a point of R_0 , $a(t_1)$ is the next minimum, and $0 \leq t \leq t_1\}$ then $M = [a_{\min}, a_{\max}]$ with $a_{\min} > 0$, $a_{\max} < \infty$ and for each ϵ and each $t \geq 0$ it holds $a_{\min} \leq a_\epsilon(t) \leq a_{\max}$.

So we have proven: in each neighbourhood of the periodic solutions of the first type there exists a set of Hausdorff dimension $D \geq 1$ of uniformly bounded aperiodic perpetually oscillating solutions, which can be integrated up to $t \rightarrow \infty$.

4 Problems with die probability measure

To give concepts like “the probability p of the appearance of a sufficiently long inflationary phase” a concrete meaning, we have to define a probability measure μ in the space V of solutions. Let us suppose we can find a hypersurface H in the space G of initial conditions such that each solution is characterized by exactly one point of H . Then V and H are homeomorphic and we need not to make a distinction between them. Let us further suppose that $H \subset G$ is defined by a suitably chosen physical quantity ψ to take the Planckian value. Then we are justified to call H the quantum boundary. By construction, H divides G into two connected components; $\psi \leq \psi_{\text{Pl}}$ defines the classical region. All classical trajectories start their evolution at H and remain in the classical region forever.

Let us remember the situation for the spatially flat Friedmann model (BELINSKY et al. (1985), Sct. 4.1.) and for the Bianchi type I model (LUKASH and SCHMIDT (1988), Sct. 4.2) before we discuss the closed Friedmann model in Sct. 4.3.

4.1 The spatially flat Friedmann model

For this case, eq. (13) reduces to $h\dot{h} = -3h\dot{\phi}^2$, i.e., each solution crosses the surface $h = h_{\text{Pl}}$ exactly once, the only exception is the flat Minkowski space-time $h \equiv 0$. And the corresponding physical quantity

$$\psi = h^2 = \phi^2 + \dot{\phi}^2 \quad (17)$$

is the energy density. The space of non-flat spatially flat Friedmann models is topologically S^1 , and equipartition of initial conditions gives a natural probability measure there. With this definition it turned out that for $m \ll m_{\text{Pl}}$ it holds

$$p \approx 1 - 8m/m_{\text{Pl}},$$

cf. e.g. MÜLLER and SCHMIDT (1989), i.e., inflation becomes quite probable. If, on the other hand, equipartition is taken at some $h_0 \ll h_{\text{Pl}} m/m_{\text{Pl}}$ then inflation is quite improbable.

The total space V of solutions has Geroch topology αS^1 , i.e., $V = S^1 \cup \{\alpha\}$, and the space itself is the only neighbourhood around the added point α (which corresponds to $h \equiv 0$), because each solution is asymptotically flat for $t \rightarrow \infty$.

4.2 The Bianchi-type I model

With the metric

$$ds^2 = dt^2 - e^{2\alpha} [e^{2(s+\sqrt{3}r)} dx^2 + e^{2(s-\sqrt{3}r)} dy^2 + e^{-4s} dz^2], \quad h = \dot{\alpha}$$

the analogue to eq. (17) is

$$\psi = h^2 = \phi^2 + \dot{\phi}^2 + \dot{r}^2 + \dot{s}^2 \quad (18)$$

and $h = h_{\text{Pl}}$ defines a sphere S^3 in eq. (18). Here all solutions cross this sphere exactly once, even the flat Minkowski spacetime: it is represented as (0 0 1)-Kasner solution α , so the space of solutions is $V = S^3/Q$, where Q is a 12-fold cover of S^3 composed of the Z_2 -gauge transformation $\phi \rightarrow -\phi$ and of the six permutations of the spatial axes.

Eq. (18) induces a natural probability measure on the space $\psi = \psi_{\text{Pl}}$ by equipartition, and the equivalence relation Q does not essentially influence this. As in Sct. 4.1., $\alpha \in V$ has only one neighbourhood: V itself. Up to this exception, V is topologically a 3-dimensional cube with boundary. One diagonal line through it represents the Kasner solution $\phi \equiv 0$. The boundary δV of V has topology S^2 and represents the axially symmetric solutions and one great circle of it the isotropic ones. (As usual, the solutions with higher symmetry form the boundary of the space of solutions.) p turns out to be

the same as in Sct. 4.1 and how ψ (eq. (18)) can be invariantly defined, is discussed in LUKASH and SCHMIDT (1988).

4.3 The closed Friedmann model

Now we come to the analogous questions concerning the closed Friedmann model. Before defining a measure, one should have a topology in a set. I feel it should be a variant of GEROCH (1969). The Geroch topology (cf. SCHMIDT (1987), especially footnote 22) is defined as follows: let $x_i = (a_i(t), \phi_i(t))$ be a sequence of solutions and $x = (a(t), \phi(t))$ a further solution. Then $x_i \rightarrow x$ in Geroch's topology, if there exist suitable gauge and coordinate transformations after which $a_i(t) \rightarrow a(t)$ and $\phi_i(t) \rightarrow \phi(t)$ converge uniformly together with all their derivatives in the interval $t \in [-\epsilon, \epsilon]$ for some $\epsilon > 0$. Because of the validity of the field equations, “with all their derivatives” may be substituted by “with their first derivatives”.

With this definition one gets just the same space V as in Sct. 3.2., eq. (15). The existence of aperiodic perpetually oscillating solutions (which go right across the region of astrophysical interest Sct. 3.5) shows that for a subset of dimension $D \geq 1$ of $R \times S^1$, Q identifies countably many points. All these points lie in a compact neighbourhood of the corresponding periodic point $(f_k, 0)$ and possess therefore (at least) one accumulation point z . At these points z , V has a highly non-Euclidean topology. Further, V has a non-compact non-Hausdorff topology. So there is no chance to define a probability measure in a natural way and no possibility to define a continuous hypersurface in the space of initial conditions which each trajectory crosses exactly once.

5 Discussion

Supposed, we had obtained a result of the type: “Each solution $a(t)$ has at least one but at most seven local maxima.” Then one could define — up to a factor $7 = O(1)$ — a probability measure. So it is just the existence of the perpetually bouncing aperiodic solutions which gives the problems. We conclude: it is not a lack of mathematical knowledge but an inherent property of the closed Friedmann model which hinders to generalize the convincing results obtained for the spatially flat model. So it is no wonder that different trials led to controversial results, cf. BELINSKY et al. (1985, 1987) and PAGE (1987). One of these results reads “inflationary and noninflationary solutions have both infinite measure”, hence, nothing is clear.

By the way, PAGE (1987) claimed to have received different results for the massive scalar field in Einstein’s theory on the one hand and for $R + \epsilon R^2$ gravity on the other hand, e.g. the existence of singularity-free solutions for the open Friedmann model only for the $R + \epsilon R^2$ model. But all these singularity-free solutions cross the critical value $R = R_c = -1/2\epsilon$ of the curvature scalar which is known to be unstable: arbitrarily small anisotropies in the initial conditions will lead to

$$C_{ijkl} C^{ijkl} \rightarrow \infty \quad \text{as} \quad R \rightarrow R_c$$

and, if we accept this point to be a singularity, too, then the results for both theories will again become the same.

Let us now discuss the results of STAROBINSKY (1978) and BARROW and MATZNER (1980) concerning the probability of a bounce. They have obtained a very low probability to get a bounce, but they used equipartition at some $h_0 \ll h_{\text{Pl}} m / m_{\text{Pl}}$. As seen in Sct. 4.1. for the spatially flat Friedmann model concerning inflation, this low probability does not hinder to get a considerable large probability if equipartition is applied at $h = h_{\text{Pl}}$. We

conclude, the probability of bouncing solutions is not a well-defined concept up to now. Well-defined is, on the other hand, some type of conditional probability. If we suppose that some fixed value a , say 10^{28} cm or so, and there some fixed value h , say 50 km/sec · Mpc or so, appear within the cosmic evolution, then the remaining degree of freedom is just the phase of the scalar field, which is the compact set S^1 as configuration space. (But this solves not all problems, because the perpetually bouncing solutions discussed in Sct. 3.5. cross this range of astrophysical interest infinitely often.) Calculating conditional probabilities instead of absolute probabilities, and, if this condition is related to our own human existence, then we have already applied the anthropic principle. (Cf. similar opinions in SINGH and PADMANABHAN (1988) concerning the so far proposed explanations of the smallness of the cosmological constant.)

The massive scalar field in a closed Friedmann model with Einstein's theory of gravity cannot explain the long inflationary stage of cosmic evolution as an absolute probable event and so some type of an anthropic principle has to be applied. See BARROW and TIPLER (1988) to this theme.

We have discussed the solutions for the minimally coupled scalar field, but many results for the conformally coupled one are similar (see e.g. TURNER and WIDROW 1988); this is explained by the existence of a conformal transformation relating between them (see SCHMIDT 1988).

The problems in the case of defining a probability measure in the set of (not necessarily spatially flat) Friedmann models are also discussed in MADSEN and ELLIS (1988). They conclude that e.g. inflation need not to solve the flatness problem. (The Gibbons-Hawking-Stewart approach gives approximately the same probability measure as the equipartition of initial conditions used here.)

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Note added in proof:

The Wheeler-de Witt equation for the massive scalar field in a closed Friedmann universe model is recently discussed by E. CALZETTA (Class. Quant. Grav. **6** (1989) L227). Possibly, this approach is the route out of the problems mentioned here.

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